

Projection of a curve onto a surface

Computing the projection of a point onto a surface is to find a closest point on the surface, and projection of a curve onto a surface is the locus of all points on the curve project onto the surface.

☐— Proj

$$\gamma := \begin{bmatrix} -0.8232 & -0.4194 & 0.3827 \\ 0.5677 & -0.6187 & 0.543 \\ 0.009 & 0.6643 & 0.7474 \end{bmatrix} \quad \text{Proj}_\gamma(x) := \left| \text{eval} \left(\text{augment} \left(\text{col}(x \cdot \gamma, 1), \text{col}(x \cdot \gamma, 3) \right) \right) \right|$$

PMesh returns a maitrx suitable for 3D plots.

$$pMesh(F\#) := \left[\begin{array}{l} F := F\# \quad nu := \text{rows}(F) - 1 \quad nv := \text{cols}(F) - 1 \\ \left[\begin{array}{l} np := 5 \quad r_{np} := [1..np] \quad r_{nv} := [1..(nv-1)] \end{array} \right] \\ \left[\begin{array}{l} M := \text{matrix}(0, 3) \quad c := [1..3] \end{array} \right] \\ \text{for } y \in [1..nu] \\ \quad \left[\begin{array}{l} \text{for } v \in [1..nv] \\ \quad \left[\begin{array}{l} r := \text{rows}(M) \quad k := r + r_{np} \\ M_{k \ c} := F \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \end{bmatrix}_{k-r} + y \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \end{bmatrix}_{k-r} + v \end{array} \right] \\ \left[\begin{array}{l} r := \text{rows}(M) \quad j := r + r_{nv} \\ M_{j \ c} := M_{(y-1) \cdot (np \cdot nv + nv - 1) + np \cdot (nv - 1) - (j - r - 1) \cdot np} \end{array} \right] \end{array} \right] \\ M \end{array} \right]$$

$$ProjC2S(\lambda(1), b, \varphi(2), B) :=$$

$$:= \left[\begin{array}{l} \text{Clear}(u, v, x, S, L, C, a, d) \quad c := [1..3] \quad \text{rng}(b) := \left[\begin{array}{l} [1..b_3] \quad b_1 + \frac{b_2 - b_1}{b_3 - 1} \cdot [1..b_3] \end{array} \right] \\ \left[\begin{array}{l} [nx \ X] := \text{rng}(\text{row}(B, 1)) \quad [ny \ Y] := \text{rng}(\text{row}(B, 2)) \end{array} \right] \\ \left[\begin{array}{l} S_{nx \ ny} := \text{eval} \left(\text{augment} \left(X_{nx}, Y_{ny}, f \left(X_{nx}, Y_{ny} \right) \right) \right) \quad k := [1..\text{length}(S)] \end{array} \right] \\ \left[\begin{array}{l} \varphi(x) := f(x_1, x_2) - x_3 \quad \varphi'_c := \frac{d}{dx_c} \varphi(x) \quad eN := \frac{\varphi'}{\text{norme}(\varphi')} \end{array} \right] \\ \left[\begin{array}{l} [nt \ T] := \text{rng}(b) \quad C_{nt \ c} := \lambda \left(\begin{array}{l} T \\ nt \end{array} \right)_c \end{array} \right] \\ \text{for } n \in nt \\ \quad \left[\begin{array}{l} A := C_{n \ c} \quad ao := S \quad \text{csort} \left(\text{augment} \left(d_k := \text{norme}(A - S_k), k \right), 1 \right)_2 \end{array} \right] \\ \left[\begin{array}{l} F(x) := \left[\begin{array}{l} \varphi(x) \\ eN_2 \cdot \begin{pmatrix} A_3 - x_3 \end{pmatrix} - eN_3 \cdot \begin{pmatrix} A_2 - x_2 \end{pmatrix} \\ eN_3 \cdot \begin{pmatrix} A_1 - x_1 \end{pmatrix} - eN_1 \cdot \begin{pmatrix} A_3 - x_3 \end{pmatrix} \end{array} \right] \quad \alpha := \text{al_nleqsolve}(ao^T, F(x)) \end{array} \right] \\ \left[\begin{array}{l} a_{n \ c} := \alpha_c \quad L_n := \text{stack}(\alpha^T, A) \end{array} \right] \\ [C \ pMesh(S) \ a \ L] \end{array} \right]$$

Returns the coordinates of the Curve (C), Surface (S), Projection (a) and Line segments between the point in the curve and the point in the surface (L).

```
pCycleC(A):= [ B:=eval(sys2mat(A)) M:= [ B 1 ] ]
               for k:=2, k<length(B), k:=k+1
               | for n∈[1..5]
               |   M rows(M)+1 := [ 10^5 10^5 ]
               |   M rows(M)+1 := B k
               | eval(mat2sys1(M))
```

Shorthand for plots

```
Plot(X):= [ C S A L ]:=X
           { Proj_Y(C)
             augment(Proj_Y(A), ".", 12, "green")
             ""
             pCycleC(Proj_Y(L))
             Proj_Y(S) }
```

Number of points:

```
nt:=50
nx:=30
ny:=30
```

Curve given by the
parametric equations

```
λ(t)=[ x(t) y(t) z(t) ] and box:=[ t1 t2 nt ]
```

Surface given by the
explicit equation

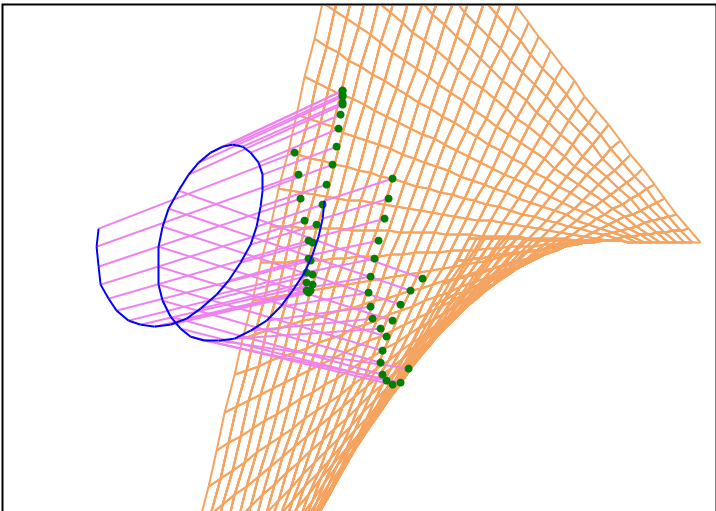
```
z=f(x,y) and Box=[ x1 x2 nx
                    y1 y2 ny ]
```

Curve

```
λ(t):=[ 0.2·t 2·sin(t) 4·cos(t) ]
Bt:=[ 20 30 nt ]
```

Surface

```
f(x,y):=x·y-4·x
Bxy:=[ -1 6 nx
        -1 6 ny ]
```



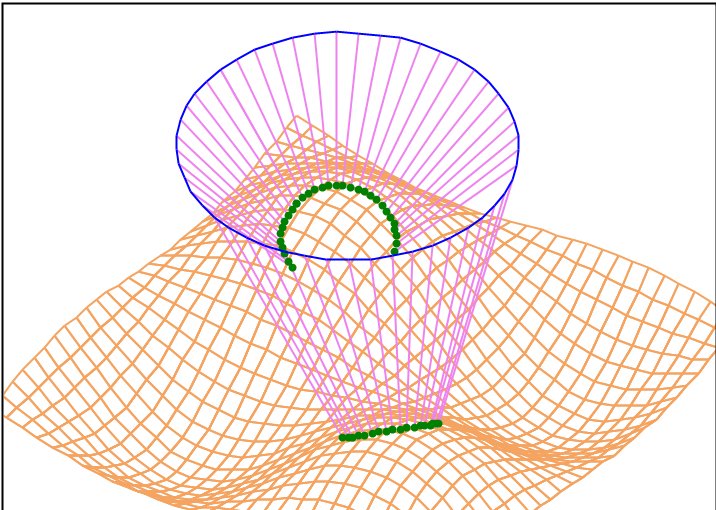
Plot(ProjC2S(λ(t), Bt, f(x,y), Bxy))

Curve

```
λ(t):=[ 2·cos(t)+0.7 2·sin(t)+0.5 3 ]
Bt:=[ 0 2·π nt ]
```

Surface

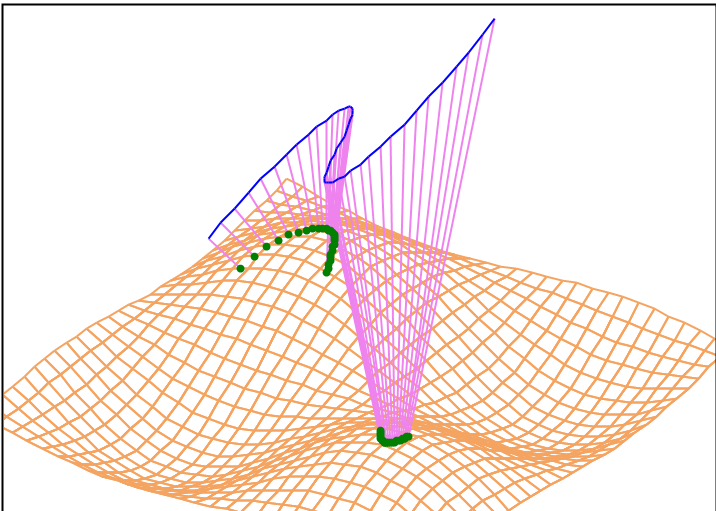
```
f(x,y):=sin(x)·sin(y)
Bxy:=[ -π π nx
        -π π ny ]
```



Plot(ProjC2S(λ(t), Bt, f(x,y), Bxy))

Same example with

$$\lambda(t) := \begin{bmatrix} 2 \cdot \cos(0.5 \cdot t) + 0.7 \cdot 2 \cdot \sin(t) + 0.5 \cdot t + 1 \end{bmatrix}$$



Plot (ProjC2S ($\lambda(t)$, Bt , f (x , y) , Bxy))

Curve

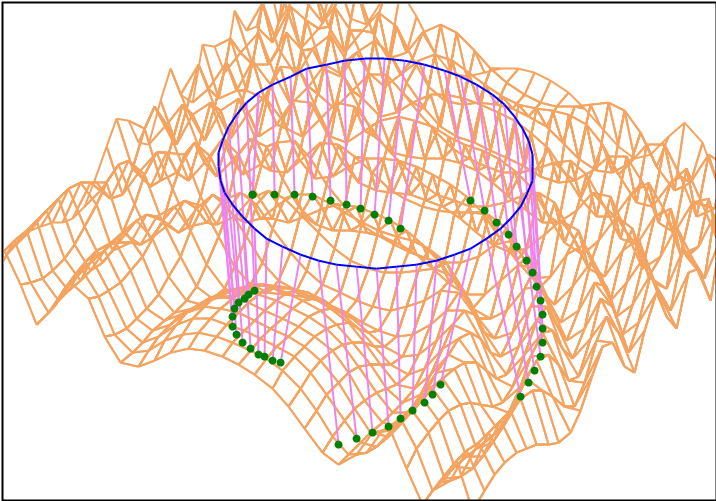
$$\lambda(t) := \begin{bmatrix} 2 \cdot \cos(t) - 1 \cdot 2 \cdot \sin(t) + 1 \cdot 3 \end{bmatrix}$$

$$Bt := \begin{bmatrix} 0 \cdot 2 \cdot \pi \cdot nt \end{bmatrix}$$

Surface

$$f(x, y) := 0.5 \cdot \cos \left(\frac{x^2}{1} + \frac{y^2}{1} \right)$$

$$Bxy := \begin{bmatrix} -4 \cdot 3.5 \cdot nx \\ -1 \cdot 6 \cdot ny \end{bmatrix}$$

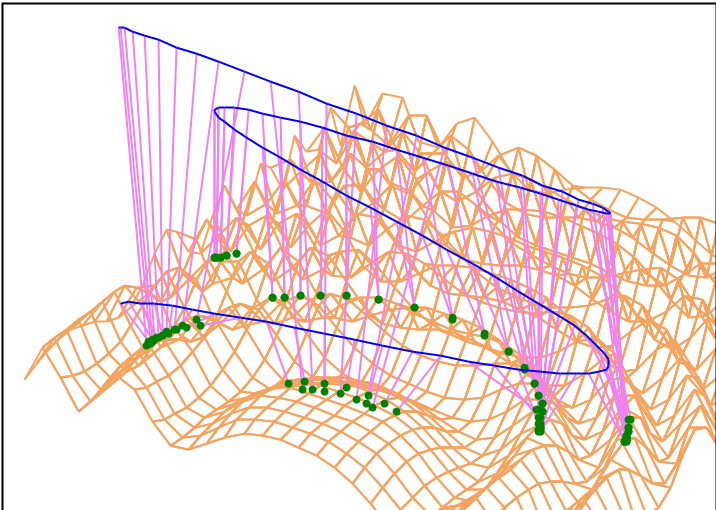


Plot (ProjC2S ($\lambda(t)$, Bt , f (x , y) , Bxy))

Same example with

$$\lambda(t) := \begin{bmatrix} 3 \cdot \cos(2 \cdot t) \cdot 2 \cdot \sin(0.5 \cdot t) \cdot \sqrt{t^2 + 1} \end{bmatrix}$$

$$Bt := \begin{bmatrix} 0 \cdot 2 \cdot \pi \cdot 2 \cdot nt \end{bmatrix}$$



Plot (ProjC2S ($\lambda(t)$, Bt , f (x , y) , Bxy))