

ODE

$$eq:=\begin{cases} u''-L.\theta''.\sin(\theta)-L.\theta'^2.\cos(\theta)+\omega^2.u-g \\ L.\theta''-u''.\sin(\theta)+g.\sin(\theta) \end{cases}$$

$$\theta''_{eq}:=isol\left(eq_2,\theta''\right) \qquad u''_{eq}:=isol\left(eq_1\left|\theta''=\theta''_{eq},u''\right.\right)$$

$$D(t,\varphi):=\begin{bmatrix} u & u' & \theta & \theta' \\ u'':=u''_{eq} \\ \left[u' & u'' & \theta' & \theta''_{eq}\right]^T \end{bmatrix}=\begin{bmatrix} \varphi_2 \\ -\frac{g\cdot\left(-1+\sin\left(\varphi_3\right)^2\right)-L\cdot\varphi_4^2\cdot\cos\left(\varphi_3\right)+\omega^2\cdot\varphi_1}{1-\sin\left(\varphi_3\right)^2} \\ \varphi_4 \\ -\frac{\sin\left(\varphi_3\right)\cdot\left(-L\cdot\varphi_4^2\cdot\cos\left(\varphi_3\right)+\omega^2\cdot\varphi_1\right)}{\left(1-\sin\left(\varphi_3\right)^2\right)\cdot L} \end{bmatrix}$$

$L:=0.5$

$k:=800$

$m:=80$

$g:=9.81$

$\omega:=\sqrt{\frac{k}{m}}$

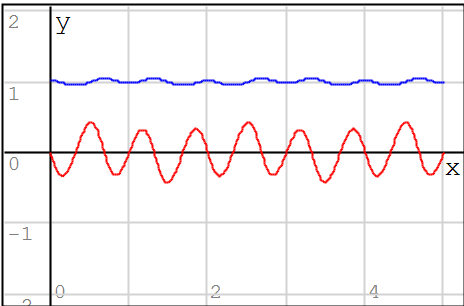
$IC:=stack(1,0,30\text{ deg},0)$

$te:=5$

$N:=500$

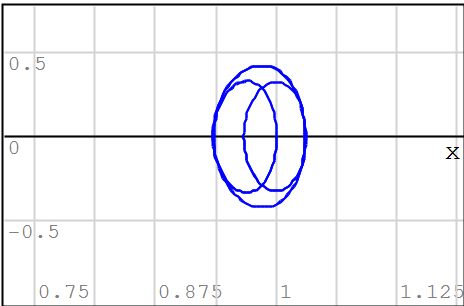
$S:=Rkadapt(IC,0,te,N,D)$

u(t) & θ(t)



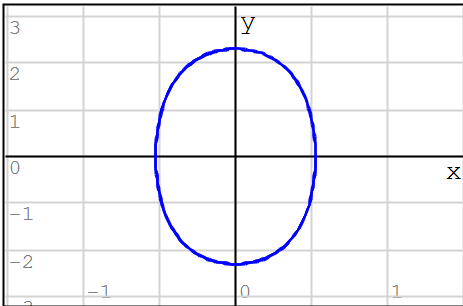
$\begin{cases} augment\left(col\left(S,1\right),col\left(S,2\right)\right) \\ augment\left(col\left(S,1\right),col\left(S,3\right)\right) \end{cases}$

u'' vs u'



$augment\left(col\left(S,2\right),col\left(S,3\right)\right)$

θ'' vs θ'



$augment\left(col\left(S,4\right),col\left(S,5\right)\right)$

+

—

Utils

+

—

RKA

+

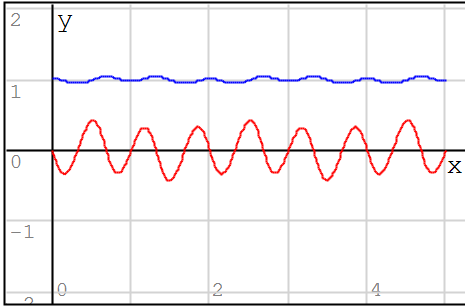
—

Vibrating Pendulum

$$DE:=\begin{cases} u''(t)-L.\theta''(t).\sin(\theta(t))-L.\theta'(t)^2.\cos(\theta(t))+\omega^2.u(t)-g=0 \\ L.\theta''(t)-u''(t).\sin(\theta(t))+g.\sin(\theta(t))=0 \\ u(0)=1 \\ \theta(0)=30\text{ deg} \\ u'(0)=0 \\ \theta'(0)=0 \end{cases}$$

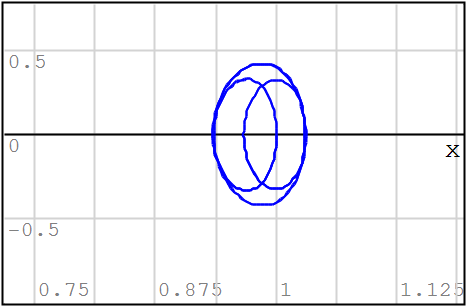
$$S := RKA \left(DE, \left\{ \begin{matrix} u(t) \\ \theta(t)' \end{matrix} \right\} \begin{bmatrix} -1 \\ -10 \end{bmatrix}, te, N \right)$$

u(t) & θ(t)



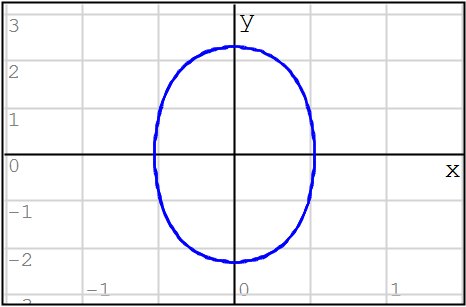
```
{augment(col(S, 1), col(S, 2))
augment(col(S, 1), col(S, 3))}
```

u'' vs u'



```
augment(col(S, 2), col(S, 3))
```

θ'' vs θ'



```
augment(col(S, 4), col(S, 5))
```

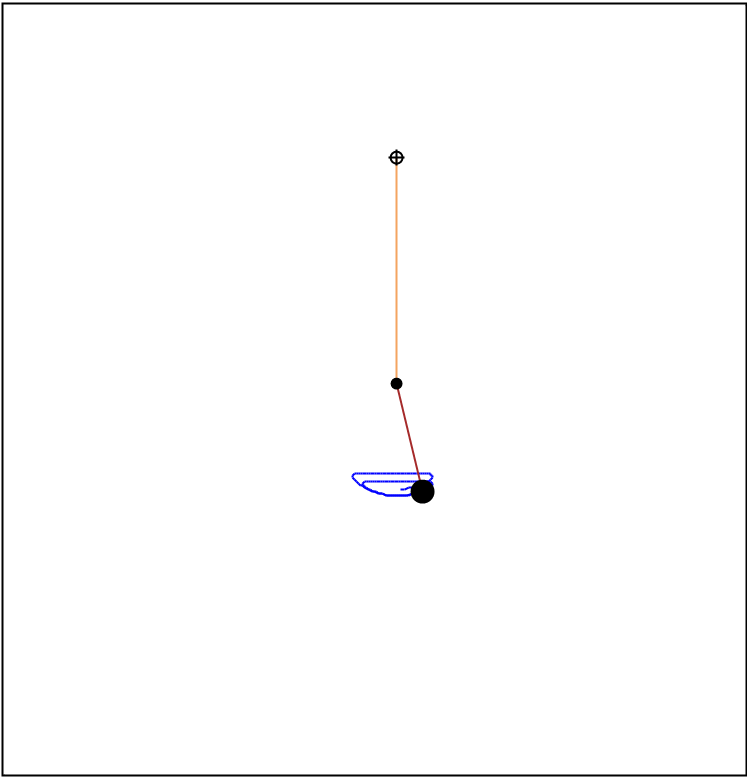
$\tau := [1..N]$

$u(\tau) := \text{col}(S, 2)_{\tau+1}$

$\theta(\tau) := \text{col}(S, 3)_{\tau+1}$

$x(\tau) := L \cdot \sin(\theta(\tau))$

$y(\tau) := u(\tau) + L \cdot \cos(\theta(\tau))$



Alvaro