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$$Y(x, a, x_U, Y_U) := a \cdot \cosh\left(\frac{x - x_U}{a}\right) - a + Y_U \quad Y'(x, a, x_U) := \sinh\left(\frac{x - x_U}{a}\right)$$

$$L_c(x_1, x_2, a, x_U) := \int_{x_1}^{x_2} \sqrt{1 + Y'(x, a, x_U)^2} dx$$

Under Tools/Options/Calulations/Integral  
accuracy I reduce it from 100 to 50

$$x_{cg}(x_1, x_2, a, x_U) := \frac{\int_{x_1}^{x_2} x \cdot \sqrt{1 + Y'(x, a, x_U)^2} dx}{L_c(x_1, x_2, a, x_U)}$$

$$Y_{cg}(x_1, x_2, a, x_U, Y_U) := \frac{\int_{x_1}^{x_2} Y(x, a, x_U, Y_U) \cdot \sqrt{1 + Y'(x, a, x_U)^2} dx}{L_c(x_1, x_2, a, x_U)}$$

$$PE(a, x_{UL}, Y_{UL}, x_{UR}, Y_{UR}) := \text{eval} \left[ \sum \begin{bmatrix} m_c g_e \cdot L_c(0 \text{ m}, x, a, x_{UL}) \cdot Y_{cg}(0 \text{ m}, x, a, x_{UL}, Y_{UL}) \\ m g_e \cdot Y(x, a, x_{UL}, Y_{UL}) \\ m_c g_e \cdot L_c(x, L, a, x_{UR}) \cdot Y_{cg}(x, L, a, x_{UR}, Y_{UR}) \end{bmatrix} \right]$$

$$L := 6 \text{ m} \quad S := 12 \text{ m} \quad H_L := 7 \text{ m} \quad H_R := 5 \text{ m} \quad m := 0.1 \text{ kg} \quad m_c := 0.1 \frac{\text{kg}}{\text{m}} \quad x := 4 \text{ m}$$

Lagrange's multipliers method function

$$LM := \frac{1}{m} \cdot \begin{bmatrix} S - (L_c(0 \text{ m}, x, a, x_{UL}) + L_c(x, L, a, x_{UR})) \\ H_L - Y(0 \text{ m}, a, x_{UL}, Y_{UL}) \\ Y(L, a, x_{UR}, Y_{UR}) - H_R \\ Y(x, a, x_{UL}, Y_{UL}) - Y(x, a, x_{UR}, Y_{UR}) \end{bmatrix} \quad \text{Lagrange's "G" function}$$

$$L(u_i, \lambda_j) = F - \left( \sum (\lambda_j \cdot G_j) \right)$$

$$LM(u\#) := \begin{bmatrix} [a \ x_{UL} \ Y_{UL} \ x_{UR} \ Y_{UR} \ \lambda_1 \ \lambda_2 \ \lambda_3 \ \lambda_4] := u\#^T \\ \text{eval}\left(\frac{1}{J} \cdot PE(a, x_{UL}, Y_{UL}, x_{UR}, Y_{UR}) - [\lambda_1 \ \lambda_2 \ \lambda_3 \ \lambda_4]^T \cdot LM\right) \end{bmatrix}$$

Target function: the transposed gradient (without dividing by h, for simplicity)

$$r\# := [1 \dots 9] \quad \varphi(u\#) := \begin{bmatrix} w\# := \text{eval}(un\# \cdot u\#) \ G\# := 0 \ LMa\# := \text{eval}(LM(w\#)) \\ G\# \ x\# := \text{eval}((LM(w\# + \text{col}(h\#, r\#)) - LMa\#)) \end{bmatrix}$$

Numerical solver: it can take a while.

$$uo\# := [1 \text{ m} \ 1 \ 1 \ 1 \ 1]^T \quad \text{guess value}$$

$$un\# := \text{eval}(\text{diag}(\overrightarrow{\text{UnitsOf}(uo\#)})) \quad h\# := \text{eval}(10^{-5} \cdot un\#) \quad \text{derivatives forward step}$$

$$[a \ x_{UL} \ Y_{UL} \ x_{UR} \ Y_{UR} \ \lambda_1 \ \lambda_2 \ \lambda_3 \ \lambda_4] := un\# \cdot \text{al_nleqsoolve}\left(\overrightarrow{\frac{uo\#}{\text{UnitsOf}(uo\#)}}, \varphi\right)^T$$

**Note for commercial use**

$$x_{UR} = 2.5708 \text{ m}$$

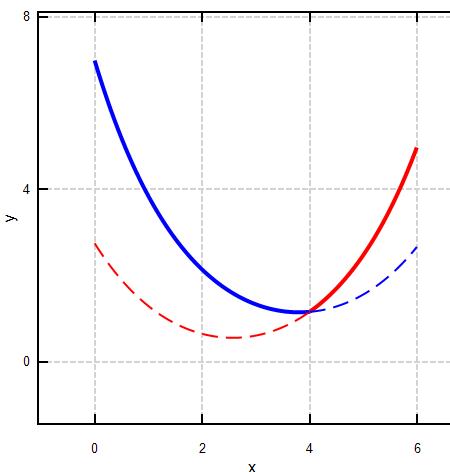
$$y_{UR} = 0.5551 \text{ m}$$

$$PE(a, x_{UL}, y_{UL}, x_{UR}, y_{UR}) = 40.6756 \text{ J}$$

Sanity check:  $\text{normi}(LM) = 0.0025$

$$x_L := \left[ (0 \text{ m}), \frac{x}{300} \dots x \right] \quad x_R := \left[ x, x + \frac{L-x}{300} \dots L \right]$$

$$Plot := \begin{cases} \text{augment} \left( \frac{x_L}{m}, \frac{\overrightarrow{Y(x_L, a, x_{UL}, y_{UL})}}{m} \right) \\ \text{augment} \left( \frac{x_R}{m}, \frac{\overrightarrow{Y(x_R, a, x_{UR}, y_{UR})}}{m} \right) \\ \text{augment} \left( \frac{x_R}{m}, \frac{\overrightarrow{Y(x_R, a, x_{UL}, y_{UL})}}{m} \right) \\ \text{augment} \left( \frac{x_L}{m}, \frac{\overrightarrow{Y(x_L, a, x_{UR}, y_{UR})}}{m} \right) \end{cases}$$



Plot

$$a := 2.5614407 \frac{\text{N}}{\text{m} - 1}$$

$$x_{UL} := 4.4116127 \text{ m}$$

$$y_{UL} := 2.163828 \text{ m}$$

$$x_{UR} := 2.1353467 \text{ m}$$

Found in Mathcad

$$y_{UR} := 1.4877577 \text{ m}$$

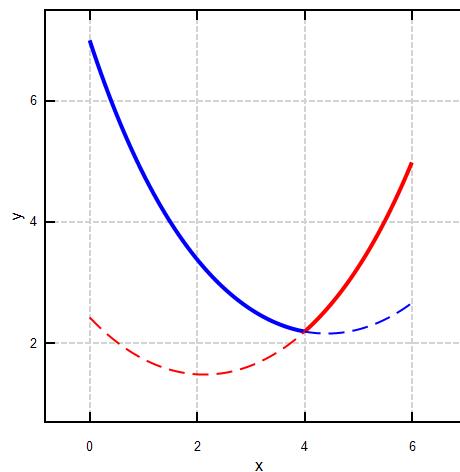
$$PE(a, x_{UL}, y_{UL}, x_{UR}, y_{UR}) = 41.275 \text{ J}$$

Sanity check:  $\text{normi}(LM) = 2$

$$LM = \begin{bmatrix} 2 \\ 7.6057 \cdot 10^{-8} \\ -5.7498 \cdot 10^{-8} \\ 6.7884 \cdot 10^{-8} \end{bmatrix} \quad \text{Not verify this equation:}$$

$$S - \left( L_c(0 \text{ m}, x, a, x_{UL}) + L_c(x, L, a, x_{UR}) \right) = 2 \text{ m}$$

$$Plot := \begin{cases} \text{augment} \left( \frac{x_L}{m}, \frac{\overrightarrow{Y(x_L, a, x_{UL}, y_{UL})}}{m} \right) \\ \text{augment} \left( \frac{x_R}{m}, \frac{\overrightarrow{Y(x_R, a, x_{UR}, y_{UR})}}{m} \right) \\ \text{augment} \left( \frac{x_R}{m}, \frac{\overrightarrow{Y(x_R, a, x_{UL}, y_{UL})}}{m} \right) \\ \text{augment} \left( \frac{x_L}{m}, \frac{\overrightarrow{Y(x_L, a, x_{UR}, y_{UR})}}{m} \right) \end{cases}$$



Plot